Using and Scaling Python

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“People are doing high performance computing with Python... how do we stop them?”

- Senior Performance Engineer
Why This talk?
• Python is popular
• It’s the de facto language for data science
• Used for a large number of scientific workflows
• It’s not uncommon for prototyping or even implementing production scientific software
• We tend to see a lot of practices and mistakes that strongly impact the performance of user Python codes
Why Python?

- If you like a programming paradigm, it’s supported
- Most functions map to what you know already
- Easy to combine with other languages
- Easy to keep code readable and maintainable
- Lets you do just about anything without changing languages
- The price is right - no license management
- Code portability
- Fully Open Source
- Very low learning curve
- Commercial support options are available
- Comes with a highly enthusiastic and helpful community
Why Not Python?

- Performance is often a secondary concern for developers and distributions
  - Most developers aren’t in HPC environments
  - Most developers aren’t in science environments
- Many tools were designed to work best in generic environments
- Language maintainers favor consistency over compatibility
- Backwards compatibility is seldom guaranteed
- Low learning curve
- It’s easy to develop a code base that works, but won’t scale
Python 2 or 3? Use Python 3.

- **Python 3 is the future** – and the future is here
- All **major libraries now work** under Python 3.5+
- Almost all **popular tools work** with Python 3.5+
- Python 3’s loader and more of the interpreter’s internals are written in Python
- Python 2 development has effectively stopped
Python at ALCF

• Every system we run is a cross-compile environment except Cooley
  • pip/distutils/setuptools/anaconda don’t play well with cross-compiling
• Blue Gene/Q Python is manually maintained:
  • Instructions on use are available in: /soft/cobalt/examples/python
  • Modules built on request, but BG/Q is end-of-life
• X86_64 offers us a lot more options:
  • Miniconda
  • Intel Python - managed and used via Conda
  • ALCF Python managed via Spack and loadable via modules
  • Bring your own Python
• We prefer users to install their own environments
• Users will need to set up their environment to use the Cray MPICH compatibility ABI and strictly build with the Intel MPI wrappers:
Python at ALCF

• Conda-based options:
  ● Theta Miniconda
    
    ```
    module avail 2>&1 | grep miniconda
    miniconda-2.7/conda-4.4.10
    miniconda-2.7/conda-4.4.10-h5py-parallel
    miniconda-2.7/conda-4.4.10-login
    miniconda-2.7/conda-4.5.4
    miniconda-2.7/conda-4.5.4-login
    miniconda-3.6/conda-4.4.10
    miniconda-3.6/conda-4.4.10-login
    miniconda-3.6/conda-4.5.4
    miniconda-3.6/conda-4.5.4-login
    ```
  ● Intel Python - managed and used via Conda
  ● Anaconda
Python at ALCF

- Built-from-source Python
  - ALCF Python managed via Spack and loadable via modules:
    `module load alcfpython/2.7.14-20180131`
    - A module that loads modules for NumPy, SciPy, MKL, h5py, mpi4py...
    - Built via Spack to emphasize performance, reproducibility, and Cray compatibility
  - Use of virtualenv is recommended - **do not mix conda and virtualenv**!
  - We’ll build any package with a Spack spec on request
Where do We want to spend our time?

- Workflows
- MPI
- MPI, OpenMP, OpenACC, or Threads
- Vectorization

Share of execution time
How does CPython work?

```python
Python 2.7.13 (default, Apr 23 2017, 16:50:50)
[GCC 4.2.1 Compatible Apple LLVM 7.3.0 (clang-703.0.31)] on darwin
Type "help", "copyright", "credits" or "license" for more information.

>>> def area_circle(r):
...     pi=3.14159
...     area=pi*r**2
...     return area
... 
>>> import dis
>>> dis.dis(area_circle.func_code)
  2           0 LOAD_CONST                           1 (3.14159)
                3 STORE_FAST                           1 (pi)
  3          6 LOAD_FAST                                    (pi)
            9 LOAD_FAST                                  (r)
            12 LOAD_CONST                                  (2)
            15 BINARY_POWER                              (area)
            16 BINARY_MULTIPLY                           (area)
            17 STORE_FAST                                  (area)
  4          20 LOAD_FAST                                  (area)
                23 RETURN_VALUE
```
How does CPython work?

```python
>>> def area_circles(R):
...     A=[]
...     for r in R:
...         A.append(area_circle(r))
...     return A
...

>>> dis.dis(area_circles.func_code)
  2           0 BUILD_LIST              0
           3 STORE_FAST               1 (A)
  3           6 SETUP_LOOP           33 (to 42)
           9 LOAD_FAST               0 (R)
          12 GET_ITER
          13 FOR_ITER              25 (to 41)
          16 STORE_FAST              2 (r)
  4          19 LOAD_FAST               1 (A)
          22 LOAD_ATTR              0 (append)
          25 LOAD_GLOBAL             1 (area_circle)
          28 LOAD_FAST               2 (r)
          31 CALL_FUNCTION            1
          34 CALL_FUNCTION            1
          37 POP_TOP
          38 JUMP_ABSOLUTE            13
          41 POP_BLOCK
  5          42 LOAD_FAST               1 (A)
          45 RETURN_VALUE
```
How does CPython work?

```python
>>> def area_circles_lc(R):
...     return [area_circle(r) for r in R]
...
>>> dis.dis(area_circles_lc.func_code)
    2             0 BUILD_LIST
    3             0 (R)
    6             0 GET_ITER
    7 FOR_ITER    18 (to 28)
    10 STORE_FAST 1 (r)
    13 LOAD_GLOBAL 0 (area_circle)
    16 LOAD_FAST   1 (r)
    19 CALL_FUNCTION 1
    22 LIST_APPEND 2
    25 JUMP_ABSOLUTE 7
    28 RETURN_VALUE
```
Threads and CPython: A Word on the GIL

To keep memory coherent, Python only allows a single thread to run in the interpreter's memory space at once. This is enforced by the Global Interpreter Lock, or GIL.

The GIL isn’t all bad. It:

• Is mostly sidestepped for I/O (files and sockets)
• Makes writing modules in C much easier
• Makes maintaining the interpreter much easier
• Makes for any easy topic of conversation
• Encourages the development of other paradigms for parallelism
• Is almost entirely irrelevant in the HPC space as it neither impacts MPI or threading within compiled modules

For the gory details, see David Beazley's talk on the GIL: https://www.youtube.com/watch?v=fwzPF2JLoeU
Takeaways on CPython

• CPython is a Read–Eval–Print Loop (REPL) environment.
• There is no look-ahead to enable optimizations.
• There is no automatic parallelism.
• Everything is evaluated piece-wise and sequentially.
• CPython was written for safety and ease of maintenance, not performance:
  o Russell Power and Alex Rubinsteyn wrote in their paper “How fast can we make interpreted Python?”:

  “In the general absence of type information, almost every instruction must be treated as INVOKE_ARBITRARY_METHOD.”

• While you can improve pure Python performance through language features running in CPython, it won’t deliver the efficiency of compiled code.
Numpy and Scipy

NumPy - your first stop for performance improvement. It provides:

- N-dimensional homogeneous arrays (ndarray)
- Universal functions (ufunc)
- built-in linear algebra, FFT, PRNGs
- Tools for integrating with C/C++/Fortran
- Heavy lifting done by optimized C/Fortran libraries such as Intel’s MKL or IBM’s ESSL

SciPy extends NumPy with common scientific computing tools

- optimization
- additional linear algebra
- integration
- interpolation
- FFT
- signal and image processing
- ODE solvers

Problems arise when NumPy isn’t well built…
NumPy and SciPy

Optimized and built with MKL via Spack

```python
# Executing the code
>>> import timeit
>>> sum([timeit.timeit('import numpy as np; np.random.random((100,100))*np.random.random((100,))', for i in range(100))])/100.0
119.68859601020813s
```

Installed via pip

Python 2.7.5 (default, Nov 6 2015, 00:28:07)
[GCC 4.8.5 20150827 (Red Hat 4.8.5-11)] on Linux

```python
# Executing the code
>>> import timeit
>>> sum([timeit.timeit('import numpy as np; np.random.random((100,100))*np.random.random((100,))', for i in range(100))])/100.0
499.9269280433655s
```
NumPy and SciPy

Using NumPy appropriately pays off:

```python
>>> import timeit
>>> import numpy as np
>>> A = np.linspace(-10, 10, 100).reshape(10, 10)
>>> B = np.linspace(-1.0, 1.0, 100).reshape(10, 10)

>>> def mat_mult(A, B):
...     """ We're assuming regular 2D NumPy matrixes with dimensions such that
...     A.shape[1] == B.shape[0]""
...     assert A.shape[1] == B.shape[0], "A[1].shape != B[0].shape"
...     C = np.zeros((A.shape[0], B.shape[1]))
...     for i in range(A.shape[0]):
...         for j in range(A.shape[1]):
...             for k in range(B.shape[1]):
...                 C[i, j] += A[i, k] * B[k, j]
...     return C

>>> if __name__ == '__main__':
...     setup_str = "from __main__ import A, B, mat_mult; import numpy as np"
...     cnt = 100000
...     manual_time = timeit.timeit("mat_mult(A, B)", number=cnt, setup=setup_str)
...     numpy_time = timeit.timeit("np.matmul(A, B)", number=cnt, setup=setup_str)
...     print("Manual Matmul x%d: %24.6fs" % (cnt, manual_time))
...     print("NumPy Matmul x%d: %24.6fs" % (cnt, numpy_time))
```

```
Manual Matmul x100000: 409.429088s
NumPy Matmul x100000: 1.660264s
```
Parallelism

DON'T CROSS THE STREAMS

Good advice is timeless
Parallelism

- Don’t cross the streams!
- Choose a form of parallelism – maybe two and stick to it! Trouble begins when you have:
  - multiple OpenMP runtimes or pthreads+OpenMP
  - multiprocessing (never the correct answer)
  - forking
- Watch affinity very carefully on the Cray – numpy and others can link threaded BLAS and LAPACK leading to more threads than you expect
Why MPI?

It is (still) the HPC paradigm for inter-process communications
• Supported by every HPC center and vendor on the planet
• APIs are stable, standardized, and portable across platforms and languages
• We’ll still be using it in 10 years…

It makes full use of HPC interconnects and hardware
• Abstracts aspects of the network that may be very system specific
• Dask, Spark, Hadoop, and Protocol Buffers use sockets or files!
• Vendors generally optimize MPI for their hardware and software

Well-supported tools for development – even for Python
• Debuggers now handle mixed language applications
• Profilers are treating Python as a first-class citizen
• Many parallel solver packages have well-developed Python interfaces

Folks have been writing Python MPI bindings since at least 1996
• David Beazley may have started this…
• Other contenders: Pypar (Ole Nielsen), pyMPI (Patrick Miller, et al), Pydusa (Timothy H. Kaiser), and Boost MPI Python (Andreas Klöckner and Doug Gregor)
• The community has mostly settled on mpi4py by Lisandro Dalcin
A bottleneck at the start: Loading Python

When working in diskless environments or from shared file systems, keep track of how much time is spent in startup and module file loading. Parallel file systems are generally optimized for large, sequential reads and writes. NFS generally serializes metadata transactions. This load time can have substantial impact on total runtimes.
mpi4py

- Pythonic wrapping of the system’s native MPI
- provides almost all MPI-1,2 and common MPI-3 features
- very well maintained
- distributed with major Python distributions
- portable and scalable
  - requires only: NumPy, Cython, and an MPI
- used to run a python application on 786,432 cores
- capabilities only limited by the system MPI
How mpi4py works...

• mpi4py jobs are launched like other MPI binaries:
  mpiexec -np ${RANKS} python ${PATH_TO_SCRIPT}
• an independent Python interpreter launches per rank
  • no automatic shared memory, files, or state
  • crashing an interpreter does crash the MPI program
  • it is possible to embed an interpreter in a C/C++ program and launch an interpreter that way
How mpi4py works...

If you crash or have trouble with simple codes, remember:

• CPython is a C binary and mpi4py is a binding
• you will likely get core files and mangled stack traces
• use ld or otool to check which MPI mpi4py is linked against
• ensure Python, mpi4py, and your code are available on all nodes and libraries and paths are correct
  • on the Cray, it may be necessary to copy
    ${CRAY_MPICH_DIR}/lib/
    into your environment’s
    ${CONDA_PREFIX}/lib/
• try running with a single rank
• rebuild with debugging symbols
mpi4py startup and shutdown

- Importing and MPI initialization
  - importing mpi4py allows you to set runtime configuration options (e.g. automatic initialization, thread_level) via mpi4py.rc()
  - by default importing the MPI submodule calls MPI_Init()
    - calling Init() or Init_thread() more than once violates the MPI standard
    - This will lead to a Python exception or an abort in C/C++
    - use Is_initialized() to test for initialization
  - MPI_Finalize() will automatically run at interpreter exit
    - there is generally no need to ever call Finalize()
    - use Is_finalized() to test for finalization if uncertain
    - calling Finalize() more than once exits the interpreter with an error and may crash C/C++/Fortran modules
mpi4py and program structure

Any code, even if after MPI.Init(), unless reserved to a given rank will run on all ranks:

```python
from mpi4py import MPI

comm = MPI.COMM_WORLD
rank = comm.Get_rank()
mpisize = comm.Get_size()

if rank%2 == 0:
    print("Hello from an even rank: %d" %(rank))

comm.Barrier()

print("Goodbye from rank %d" %(rank))
```
mpi4py and datatypes

• Python objects, unless they conform to a C data type, are pickled
  • pickling and unpickling have significant compute overhead
  • overhead impacts both senders and receivers
  • pickling may also increase the memory size of an object
  • use the lowercase methods, eg: recv(), send()
• Picklable Python objects include:
  • None, True, and False
  • integers, long integers, floating point numbers, complex numbers
  • normal and Unicode strings
  • tuples, lists, sets, and dictionaries containing only picklable objects
  • functions defined at the top level of a module
  • built-in functions and classes defined at the top level of a module
  • instances of such classes whose __dict__() or the result of calling __getstate__() is picklable
mpi4py and datatypes

- Buffers, MPI datatypes, and NumPy objects aren’t pickled
  - transmitted near the speed of C/C++
  - NumPy datatypes are autoconverted to MPI datatypes
  - buffers may need to be described as a 2/3-list/tuple
    - [data, MPI.DOUBLE] for a single double
    - [data, count, MPI.INT] for an array of integers
- custom MPI datatypes are still possible
  - use the capitalized methods, e.g.: `Recv()`, `Send()`
- When in doubt: can it be represented as a memory buffer or only as PyObject?
mpi4py: collectives and operations

- Collectives operating on Python objects are naive
- For the most part collective reduction operations on Python objects are serial
- Casing convention applies to methods:
  - lowercase methods will work for general Python objects (albeit slowly)
  - uppercase methods will work for NumPy/MPI data types at near C speed
mpi4py: Parallel I/O

- All 30-something MPI-2 methods are supported
- conventional Python I/O is not MPI safe!
  - safe to read files, though there might be locking issues
  - write a separate file per rank if you must use Python I/O
- h5py 2.2.0 and later support parallel I/O
  - hdf5 must be built with parallel support
    - make sure your hdf5 matches your MPI
  - h5pcc must be present
  - check things with: h5pcc -showconfig
  - hdf5 and h5py from Anaconda are serial!
- anything which modifies the structure or metadata of a file must be done collectively
- Generally as simple as:
  ```python
  f = h5py.File('parallel_test.hdf5', 'w',
               driver='mpio', comm=MPI.COMM_WORLD)
  ```
**Profiling Python application**

- Right tool for high performance application profiling at all levels
  - Function-level and line-level hotspot analysis, down to disassembly
  - Call stack analysis
  - Low overhead
  - Mixed-language, multi-threaded application analysis
  - Advanced hardware event analysis for native codes (Cython, C++, Fortran) for cache misses, branch misprediction, etc.

<table>
<thead>
<tr>
<th>Feature</th>
<th>cProfile</th>
<th>Line_profiler</th>
<th>Intel® VTune™ Amplifier</th>
</tr>
</thead>
<tbody>
<tr>
<td>Profiling technology</td>
<td>Event</td>
<td>Instrumentation</td>
<td>Sampling, hardware events</td>
</tr>
<tr>
<td>Analysis granularity</td>
<td>Function-level</td>
<td>Line-level</td>
<td>Line-level, call stack, time windows, hardware events</td>
</tr>
<tr>
<td>Intrusiveness</td>
<td>Medium (1.3-5x)</td>
<td>High (4-10x)</td>
<td>Low (1.05-1.3x)</td>
</tr>
<tr>
<td>Mixed language programs</td>
<td>Python</td>
<td>Python</td>
<td>Python, Cython, C++, Fortran</td>
</tr>
</tbody>
</table>
Using VTune from command line

```
amplxe-cl -collect hotspots \ 
    -knob sampling-interval=1 \ 
    -knob analyze-openmp=true \ 
    -r dir_name_hs \ 
    -- python script.py
```

Analysis type

Analysis parameters, knobs

```
amplxe-cl -archive -r dir_name_hs
```

Make trace folder relocatable

```
amplxe-gui ./dir_name_hs/ dir_name_hs.amplxe
```

Analyse in GUI on laptop
VTune trace at a glance [summary tab]

**Elapsed Time**: 2.916s
- **CPU Time**: 61.890s
- **Effective Time**: 60.079s
- **Spin Time**: 0.240s
- **Overhead Time**: 1.571s

**Top Hotspots**

This section lists the most active functions in your application. Optimizing these hotspot functions typically results in improving overall application performance.

<table>
<thead>
<tr>
<th>Function</th>
<th>Module</th>
<th>CPU Time</th>
</tr>
</thead>
<tbody>
<tr>
<td>pow</td>
<td>libm-2.17.so</td>
<td>24.106s</td>
</tr>
<tr>
<td>DOUBLE_add.h</td>
<td>umath.cpython-36m-x86_64-linux-gnu.so</td>
<td>6.187s</td>
</tr>
<tr>
<td>DOUBLE_mulpy.h</td>
<td>umath.cpython-36m-x86_64-linux-gnu.so</td>
<td>4.656s</td>
</tr>
<tr>
<td>[MKL_BLAS]@dcopy</td>
<td>libmkl_intel_thread.so</td>
<td>4.365s</td>
</tr>
<tr>
<td>vdRngUniform</td>
<td>libmkl_intel_lp64.so</td>
<td>4.032s</td>
</tr>
<tr>
<td>[Others]</td>
<td></td>
<td>19.554s</td>
</tr>
</tbody>
</table>

**CPU Usage Histogram**

This histogram displays a percentage of the wall time the specific number of CPUs were running simultaneously. Spin and Overhead time adds to the idle CPU usage value.
Bottom-up view

Hot functions

Hot call stack

self-time, excluding callees

Helps analysis to filter-in on the OMP master thread
Top-down view

**total time, including callees**
Python mode vs. native mode

amplxe-cl ... -mrte-mode=native -- python script.py ← treat python application as a binary

VTune will no see python functions, only C functions behind them.

Useful if the default -mrte-mode=python is running into issues.

amplxe-cl .... -mrte-mode=native -run-pass-thru=--no-altstack -- python script.py

On Linux, if “stack size too small” error seen.
Cython: seen as generated C
Common problematic patterns

- **Coarse Grain Locks**
- **High Lock Contention**
- **Load Imbalance**

Low Concurrency
Intel® Trace Collector & Analyzer

LD_PRELOAD="/opt/intel/itac/2018.1.017/intel64/slib/libVT.so $CONDA_PREFIX/lib/libmpi.so" \ mpiexec -n 4 python script.py

... mpiexec -gtool "amplxe-cl -collect hpc-performance -r result:1-4" ...

Use VTune to analyze node-level performance. Can also use Intel® Advisor: advixe-cl
Summary view

**Summary view**

**Summary:** python.stf

Total time: 1.34 sec. Resources: 4 processes, 1 node.

**Ratio**

This section represents a ratio of all MPI calls to the rest of your code in the application.

- Serial Code - 1.3 sec 96.8%
- OpenMP - 0 sec 0%
- MPI calls - 0.0424 sec 3.1%

**Top MPI functions**

This section lists the most active MPI functions from all MPI calls in the application.

- **MPI_Finalize**: 0.0128 sec (9.55%)
- **MPI_Gather**: 0.0111 sec (8.17%)
- **MPI_Gather**: 0.0109 sec (8.12%)
- **MPI_Scatter**: 0.00751 sec (5.59%)
- **MPI_Scatter**: 0.00011 sec (0.00819%)

**Where to start with analysis**

For deep analysis of the MPI-bound application click "Continue >" to open the tracefile View and leverage the **Intel® Trace Analyzer** functionality:

- Performance Assistant - to identify possible performance problems
- Imbalance Diagram - for detailed imbalance overview
- Tagging/Filtering - for thorough customizable analysis

To optimize node-level performance use:

**Intel® VTune™ Amplifier**

- algorithmic level tuning with hpc-performance and threading efficiency analysis
- microarchitecture level tuning with general exploration and bandwidth analysis

**Intel® Advisor**

- vectorization optimization and thread prototyping.

Use the following command lines to run these tools for the most CPU-bound rank.

**Intel® VTune™ Amplifier**:

```
#mpirun -gtool “amplxe-cl -collect hpc-performance -r result:2” -n 4 -ppm 1 python sources/adv_fast_distributed_mpi.py
```

**Intel® Advisor**:

```
#mpirun -gtool “advexe-cl -collect survey:2” -n 4 -ppm 1 python sources/adv_fast_distributed_mpi.py
```
Time-line view in traceanalyzer
Enumerated admonishments

- Benchmark and profile as you develop
- Control your environment
- Ask if you can do an operation with NumPy or SciPy
- Watch your data types – use NumPy datatypes
- Never mix forking and threading – i.e.: Python multiprocessing
- Avoid threading in Python – use threads in compiled modules
- Check the build configurations of your important Python modules
- Beware of thread affinity:
  ```
  aprun -n ... -N ... -e KMP_AFFINITY=none -d ... -j ...
  ```
- Watch startup times carefully
- Search before you write code – someone else has likely already implemented the solution you seek
- On Cray systems, you’ll need the -b flag to aprun with any sort of environment manager
Questions?

See also:

ECP Python Tutorial:
https://github.com/wscullin/ecp_python_tutorial
by William Scullin (ALCF), Matt Belhorn (OLCF), and Rollin Thomas (NERSC)

Intel Python Distribution: